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## ON DEFORMATION PECULIARITIES OF TWO THIN STRIPS WITH A MICROCRACK AT THE INTERFACE

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**Abstract.** *This study examines the problem of plane strain in a crack between two isotropic, linearly elastic layers, one of which is rigidly fixed. The Fourier integral transform method was applied, reducing the initial system of differential equations to a system of ordinary differential equations. A system of singular integral equations (SIE) was constructed to satisfy the boundary conditions of the problem. By discretizing this system, it was further reduced to a system of linear algebraic equations (SLAE).*

*Analytical expressions were obtained for the crack opening and stress distribution along the interface, allowing the calculation of the energy release rate (ERR) at the crack tips. A numerical illustration of the results was conducted, including graphs of crack opening and stress dependence for various layer thicknesses and Young's moduli.*

*Comparison between analytical and numerical solutions, obtained using the finite element method (FEM), showed good agreement for the case of a microcrack with variable characteristics of the thin coating and the lower layer. A significant influence of the coating thickness on the energy release rate was identified.*

**Key words:** *microcrack, stress-strain state, singular integral equations, energy release rate, crack opening.*

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### 1. INTRODUCTION

In modern materials science, where thin films and overlays are widely used to reinforce and protect structures, the reliability of connections between such coatings and base materials remains a crucial aspect. These connections often suffer from microcracks at layer interfaces, which can compromise the integrity of the structure and reduce its operational performance. Microcracks at the boundary between two thin strips or a strip and an overlay become critical as they serve as zones of concentrated stress, which promotes further material degradation. Understanding the deformation behavior and the impact of microcracks at these interfaces is essential for predicting the reliability of complex multilayered systems.

Investigation of cracks forming at the fixed edges of thin strips is of particular interest, as such defects can cause local stress distribution changes, affecting the stability and strength of the structure. Analyzing the interaction between a thin strip and an overlay, taking into account the presence of a microcrack at their connection, deepens the understanding of micro-level fracture processes and helps develop approaches to prevent them.

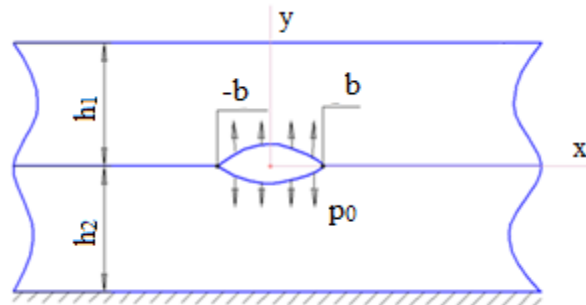
Many studies have examined cracks between two materials, with recent publications focusing on different types of stress-strain states, materials, loading conditions, and crack

geometries [1–5]. Studies on cracks in homogeneous and heterogeneous strips are especially notable. In particular, work [6] analyzes the stress-strain state of three heterogeneous materials with internal and interphase cracks. Crack investigation in a nonhomogeneous medium with a constant Poisson's ratio and an exponentially varying Young's modulus is covered in [7], while [8] explores cases where one material has nonhomogeneous properties in the interaction zone. Study [9] examines a central crack in an infinite strip under internal pressure and concentrated forces at its edges. It is important to note that these studies primarily address internal and interfacial macrocracks. Interaction of an electrode with an electrically conductive interface crack was considered in [10] and an analysis of pre-fracture zones for an electrically permeable crack in an interlayer between piezoelectric materials has been performed in [11]. The works [12–14] are devoted to the study of cracks and contact problems taking into account the elastic-plastic behavior of materials.

This work focuses on the stress-strain analysis in the zone of a microcrack at the boundary between two isotropic layers of different thicknesses, with one layer rigidly fixed. This analysis provides essential information on the deformation behavior of multilayered structures with cracks, which can improve designs of structures including thin films and overlays under different mechanical loads.

## 2. EXPERIMENTAL METHODS

Consider the problem of plane deformation of a crack  $|x| \leq b$  between two isotropic, linearly elastic, infinite layers of thickness  $h_1$  and  $h_2$ , with the lower layer rigidly fixed  $y = -h_2$ . The crack is assumed to be open due to uniform internal pressure  $p_0$  applied to its edges (Fig. 1).



**Figure 1.** The geometry and load of the problem

To solve this problem, it is necessary to solve a boundary value problem, which is described by a system of second-order partial differential equations  $p_0$

$$\mu_i \Delta^2 u^{(i)}(x, y) + \frac{2\mu_i}{\kappa_i - 1} \frac{\partial}{\partial x} \left( \frac{\partial u^{(i)}(x, y)}{\partial x} + \frac{\partial v^{(i)}(x, y)}{\partial y} \right) = 0, \quad (1)$$

$$\mu_i \Delta^2 v^{(i)}(x, y) + \frac{2\mu_i}{\kappa_i - 1} \frac{\partial}{\partial x} \left( \frac{\partial u^{(i)}(x, y)}{\partial x} + \frac{\partial v^{(i)}(x, y)}{\partial y} \right) = 0, \quad (2)$$

where  $\mu_i$  and  $\nu_i$  are the shear modulus and Poisson's ratio, respectively,  $i = 1, 2$ ,

$$\kappa_i = \begin{cases} 3 - 4\nu_i & \text{– for plane deformation,} \\ \frac{3 - \nu_i}{1 + \nu_i} & \text{– for the plane stress state.} \end{cases}$$

The boundary conditions due to symmetry, can be written as:

$$\tau_{xy}^{(1)}(x, h_1) = 0, \quad 0 \leq x < \infty, \tag{3}$$

$$\sigma_{yy}^{(1)}(x, h_1) = 0, \quad 0 \leq x < \infty, \tag{4}$$

$$\frac{\partial v^{(2)}(x, -h_2)}{\partial x} = 0, \quad \frac{\partial u^{(2)}(x, -h_2)}{\partial x} = 0, \quad 0 \leq x < \infty \tag{5}$$

$$\sigma_{yy}^{(1)}(x, 0) = \sigma_{yy}^{(2)}(x, 0), \quad 0 \leq x < \infty, \tag{6}$$

$$\tau_{xy}^{(1)}(x, 0) = \sigma_{yy}^{(1)}(x, 0) = 0, \quad 0 \leq x \leq b. \tag{7}$$

Applying the Fourier integral transforms to equations (1) and (2):

$$\bar{u}(\alpha, y) = \int_0^\infty u(x, y) \sin(\alpha x) dx, \quad \bar{v}(\alpha, y) = \int_0^\infty v(x, y) \cos(\alpha x) dx,$$

we obtain a system of ordinary differential equations. After finding the general solution of this system and applying the inverse Fourier transform,

$$u(x, y) = \frac{2}{\pi} \int_0^\infty \bar{u}(\alpha, y) \sin(\alpha x) d\alpha, \quad v(x, y) = \frac{2}{\pi} \int_0^\infty \bar{v}(\alpha, y) \cos(\alpha x) d\alpha,$$

we will have

$$u^{(1)}(x, y) = \frac{2}{\pi} \int_0^\infty [(A_1 + B_1 y) e^{-\alpha y} + (C_1 + D_1 y) e^{\alpha y}] \sin(\alpha x) d\alpha, \tag{8}$$

$$v^{(1)}(x, y) = \frac{2}{\pi} \int_0^\infty \left[ \left( A_1 + \left( \frac{k_1}{\alpha} + y \right) B_1 \right) e^{-\alpha y} + \left( -C_1 + \left( \frac{k_1}{\alpha} - y \right) D_1 \right) e^{\alpha y} \right] \cos(\alpha x) d\alpha, \tag{9}$$

$$u^{(2)}(x, y) = \frac{2}{\pi} \int_0^\infty [(A_2 + B_2 y) e^{-\alpha y} + (C_2 + D_2 y) e^{\alpha y}] \sin(\alpha x) d\alpha, \tag{10}$$

$$v^{(2)}(x, y) = \frac{2}{\pi} \int_0^\infty \left[ \left( A_2 + \left( \frac{k_2}{\alpha} + y \right) B_2 \right) e^{-\alpha y} + \left( -C_2 + \left( \frac{k_2}{\alpha} - y \right) D_2 \right) e^{\alpha y} \right] \cos(\alpha x) d\alpha, \tag{11}$$

where  $A_1, B_1, C_1, D_1, A_2, B_2, C_2, D_2$  are unknown constants.

Using the equations (8)–(11) and applying Hook’s law we obtain

$$\begin{aligned} \tau_{xy}^{(1)}(x, y) &= \frac{4\mu_1}{\pi} \int_0^\infty \left\{ \left[ -\alpha(A_1 + B_1 y) - B_1 \frac{\kappa_1 - 1}{2} \right] e^{-\alpha y} + \right. \\ &+ \left. \left[ \alpha(C_1 + D_1 y) - D_1 \frac{\kappa_1 - 1}{2} \right] e^{\alpha y} \right\} \sin(\alpha x) d\alpha = 0, \\ \tau_{xy}^{(2)}(x, y) &= \frac{4\mu_2}{\pi} \int_0^\infty \left\{ \left[ -\alpha(A_2 + B_2 y) - B_2 \frac{\kappa_2 - 1}{2} \right] e^{-\alpha y} + \right. \\ &+ \left. \left[ \alpha(C_2 + D_2 y) - D_2 \frac{\kappa_2 - 1}{2} \right] e^{\alpha y} \right\} \sin(\alpha x) d\alpha = 0, \end{aligned} \quad (12)$$

$$\begin{aligned} \sigma_{yy}^{(1)}(x, y) &= \frac{4\mu_1}{\pi} \int_0^\infty \left\{ \left[ -\alpha(A_1 + B_1 y) - B_1 \frac{1 + \kappa_1}{2} \right] e^{-\alpha y} + \right. \\ &+ \left. \left[ -\alpha(C_1 + D_1 y) + D_1 \frac{1 + \kappa_1}{2} \right] e^{\alpha y} \right\} \cos(\alpha x) d\alpha = 0, \\ \sigma_{yy}^{(2)}(x, y) &= \frac{4\mu_2}{\pi} \int_0^\infty \left\{ \left[ -\alpha(A_2 + B_2 y) - B_2 \frac{1 + \kappa_2}{2} \right] e^{-\alpha y} + \right. \\ &+ \left. \left[ -\alpha(C_2 + D_2 y) + D_2 \frac{1 + \kappa_2}{2} \right] e^{\alpha y} \right\} \cos(\alpha x) d\alpha = 0. \end{aligned} \quad (13)$$

Let us introduce the unknown functions

$$f_1(x) = \frac{\partial u^{(1)}(x, 0)}{\partial x} - \frac{\partial u^{(2)}(x, 0)}{\partial x}, \quad f_2(x) = \frac{\partial v^{(1)}(x, 0)}{\partial x} - \frac{\partial v^{(2)}(x, 0)}{\partial x} \quad \text{for } 0 \leq x \leq b. \quad (14)$$

Then, by satisfying the boundary conditions (4)–(6) and equation (14), using (8)–(13), and applying the inverse Fourier transforms to the resulting equations, we arrive at the following system of linear algebraic equations with respect to where  $A_1, B_1, C_1, D_1, A_2, B_2, C_2, D_2$ :

$$\begin{aligned} -\alpha e^{-\alpha h_1} A_1 + \left( -\alpha h_1 - \frac{\kappa_1 - 1}{2} \right) e^{-\alpha h_1} B_1 + \alpha e^{\alpha h_1} C_1 + \left( \alpha h_1 - \frac{\kappa_1 - 1}{2} \right) e^{\alpha h_1} D_1 &= 0, \\ -\alpha e^{-\alpha h_1} A_1 + \left( -\alpha h_1 - \frac{\kappa_1 + 1}{2} \right) e^{-\alpha h_1} B_1 - \alpha e^{\alpha h_1} C_1 + \left( -\alpha h_1 + \frac{\kappa_1 + 1}{2} \right) e^{\alpha h_1} D_1 &= \frac{P}{4\mu_1} \cos(\alpha a), \\ e^{\alpha h_2} A_2 - h_2 e^{\alpha h_2} B_2 + e^{-\alpha h_2} C_2 - h_2 e^{-\alpha h_2} D_2 &= 0, \\ e^{\alpha h_2} A_2 + \left( \frac{\kappa_2}{\alpha} - h_2 \right) e^{\alpha h_2} B_2 - e^{-\alpha h_2} C_2 + \left( \frac{\kappa_2}{\alpha} - h_2 \right) e^{-\alpha h_2} D_2 &= 0, \end{aligned}$$

$$-\alpha K A_1 - K \frac{\kappa_1 - 1}{2} B_1 + \alpha K C_1 - \frac{\kappa_1 - 1}{2} K D_1 + \alpha A_2 + \frac{\kappa_2 - 1}{2} B_2 - \alpha C_2 + \frac{\kappa_2 - 1}{2} D_2 = 0,$$

$$A_1 + C_1 - A_2 - C_2 = \frac{1}{\alpha} \bar{f}_1(\alpha),$$

$$A_1 + \frac{\kappa_1}{\alpha} B_1 - C_1 + \frac{\kappa_1}{\alpha} D_1 - A_2 - \frac{\kappa_2}{\alpha} B_2 + C_2 - \frac{\kappa_2}{\alpha} D_2 = \frac{1}{\alpha} \bar{f}_2(\alpha),$$

where

$$K = \frac{\mu_1}{\mu_2}, \quad \bar{f}_2(\alpha) = \int_0^\infty f_2(x) \sin(\alpha x) dx, \quad \bar{f}_1(\alpha) = \int_0^\infty f_1(x) \cos(\alpha x) dx.$$

The solution to this system was obtained using the computer algebra system Wolfram Mathematica 13.1, and based on it, the expressions for the stresses along the interface were found in the following form:

$$\tau_{xy}^{(l)}(x, 0) = \frac{4\mu_1}{\pi} \int_0^\infty [H_{11}(\alpha) \bar{f}_1(\alpha) + H_{12}(\alpha) \bar{f}_2(\alpha)] \sin(\alpha x) d\alpha, \quad (15)$$

$$\sigma_{yy}^{(l)}(x, 0) = \frac{4\mu_1}{\pi} \int_0^\infty [H_{21}(\alpha) \bar{f}_1(\alpha) + H_{22}(\alpha) \bar{f}_2(\alpha)] \cos(\alpha x) d\alpha, \quad (16)$$

where the functions  $H_{ij}(\alpha)$  are provided in the appendix.

By evaluating  $H_{ij}^\infty = H_{ij}(\alpha)$  at  $\alpha \rightarrow \infty$ , we can rewrite expressions (15) and (16) as:

$$\begin{aligned} \tau_{xy}^{(l)}(x, 0) &= \frac{4\mu_1}{\pi} \int_0^\infty [\tilde{H}_{11}(\alpha) \bar{f}_1(\alpha) + \tilde{H}_{12}(\alpha) \bar{f}_2(\alpha)] \sin(\alpha x) d\alpha + \\ &+ \frac{4\mu_1}{\pi} \int_0^\infty [H_{11}^\infty \bar{f}_1(\alpha) + H_{12}^\infty \bar{f}_2(\alpha)] \sin(\alpha x) d\alpha, \end{aligned} \quad (17)$$

$$\begin{aligned} \sigma_{yy}^{(l)}(x, 0) &= \frac{4\mu_1}{\pi} \int_0^\infty [\tilde{H}_{21}(\alpha) \bar{f}_1(\alpha) + \tilde{H}_{22}(\alpha) \bar{f}_2(\alpha)] \cos(\alpha x) d\alpha + \\ &+ \frac{4\mu_1}{\pi} \int_0^\infty [H_{21}^\infty \bar{f}_1(\alpha) + H_{22}^\infty \bar{f}_2(\alpha)] \cos(\alpha x) d\alpha, \end{aligned} \quad (18)$$

where

$$\tilde{H}_{ij}(\alpha) = H_{ij}(\alpha) - H_{ij}^\infty, \quad H_{11}^\infty = H_{22}^\infty = -\frac{1 + K + \kappa_1 + \kappa_2 K}{\Delta},$$

$$H_{12}^{\infty} = H_{21}^{\infty} = \frac{1 - K - \kappa_1 + \kappa_2 K}{\Delta}, \quad \Delta = 2(K + \kappa_1)(1 + \kappa_2 K).$$

Considering the following integral formulas:

$$\int_0^{\infty} e^{-\eta\alpha} \sin \alpha (x \mp y) d\alpha = \frac{1}{x \mp y} \quad \text{for } \eta \rightarrow 0,$$

$$\int_0^{\infty} f_i(t) \int_0^{\infty} \sin(\alpha t) \sin(\alpha x) d\alpha dt = \frac{\pi}{2} f_i(x), \quad i = 1, 2,$$

and taking into account the symmetry relative to the axis  $y$ , the expressions for the stresses (17), (18), can be represented in the following form:

$$\begin{aligned} \tau_{xy}^{(1)}(x, 0) = & \frac{2\mu_1}{\pi} \int_{-b}^b f_1(t) \int_0^{\infty} \tilde{H}_{11}(\alpha) [-\sin \alpha(t-x)] d\alpha dt + \\ & + \frac{2\mu_1}{\pi} \int_{-b}^b f_2(t) \int_0^{\infty} \tilde{H}_{12}(\alpha) \cos \alpha(t-x) d\alpha dt - 2\mu_1 \left[ H_{11}^{\infty} \frac{1}{\pi} \int_{-b}^b \frac{f_1(t)}{t-x} dt - H_{12}^{\infty} f_2(x) \right], \end{aligned} \quad (19)$$

$$\begin{aligned} \sigma_{yy}^{(1)}(x, 0) = & \frac{2\mu_1}{\pi} \int_{-b}^b f_1(t) \int_0^{\infty} \tilde{H}_{21}(\alpha) \cos \alpha(t-x) d\alpha dt - \\ & 2\mu_1 \left[ H_{21}^{\infty} f_1(x) + H_{22}^{\infty} \frac{1}{\pi} \int_{-b}^b \frac{f_2(t)}{t-x} dt \right] \\ & + \frac{2\mu_1}{\pi} \int_{-b}^b f_2(t) \int_0^{\infty} \tilde{H}_{22}(\alpha) [\sin \alpha(t-x)] d\alpha dt. \end{aligned} \quad (20)$$

Introducing the designations:

$$\begin{aligned} M_{11}(x, t) = & \int_0^{\infty} \tilde{H}_{11}(\alpha) \sin \alpha(t-x) d\alpha, \quad M_{12}(x, t) = \int_0^{\infty} \tilde{H}_{12}(\alpha) \cos \alpha(t-x) d\alpha, \\ M_{21}(x, t) = & \int_0^{\infty} \tilde{H}_{21}(\alpha) \cos \alpha(t-x) d\alpha, \quad M_{22}(x, t) = \int_0^{\infty} \tilde{H}_{22}(\alpha) \sin \alpha(t-x) d\alpha, \end{aligned}$$

formulas (20) can be written in the following form:

$$\frac{\tau_{xy}^{(1)}(x, 0)}{2\mu_1} = -\frac{H_{11}^{\infty}}{\pi} \int_{-b}^b \frac{f_1(t)}{t-x} dt + H_{12}^{\infty} f_2(x) - \frac{1}{\pi} \int_{-b}^b f_1(t) M_{11}(x, t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{12}(x, t) dt, \quad (21)$$

$$\frac{\sigma_{yy}^{(1)}(x, 0)}{2\mu_1} = -H_{21}^{\infty} f_1(x) - \frac{H_{22}^{\infty}}{\pi} \int_{-b}^b \frac{f_2(t)}{t-x} dt + \frac{1}{\pi} \int_{-b}^b f_1(t) M_{21}(x, t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{22}(x, t) dt. \quad (22)$$

Satisfying further the boundary conditions (7), we arrive at the following system of singular integral equations:

$$-\frac{H_{11}^\infty}{\pi} \int_{-b}^b \frac{f_1(t)}{t-x} dt + H_{12}^\infty f_2(x) - \frac{1}{\pi} \int_{-b}^b f_1(t) M_{11}(x,t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{12}(x,t) dt = 0, \quad (23)$$

$$-H_{21}^\infty f_1(x) - \frac{H_{22}^\infty}{\pi} \int_{-b}^b \frac{f_2(t)}{t-x} dt + \frac{1}{\pi} \int_{-b}^b f_1(t) M_{21}(x,t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{22}(x,t) dt = \frac{p_0}{2\mu_1}. \quad (24)$$

The additional conditions for this system are as follows:

$$\int_{-b}^b f_1(t) dt = 0, \quad \int_{-b}^b f_2(t) dt = 0. \quad (25)$$

The solution of the system (23), (24) has an oscillatory singularity near the crack tips, but according to [15], for determining the global fracture parameters and the energy release rate (ERR), the oscillation can be neglected, and the solution of this system can be found in the form:

$$f_i(t) = \frac{f_i^*(t)}{\sqrt{b^2 - t^2}}, \quad i = 1, 2. \quad (26)$$

Substituting (26) into (23)–(25) and transitioning to the interval  $[-1, 1]$  using the substitution  $x = br$ ,  $t = bs$ , we obtain:

$$-\frac{H_{11}^\infty}{\pi} \int_{-1}^1 \frac{\psi_1^*(s) ds}{(s-r)\sqrt{1-s^2}} + \frac{H_{12}^\infty \psi_2^*(r)}{\sqrt{1-r^2}} - \frac{b}{\pi} \int_{-1}^1 \left[ M_{11}(x,t) \frac{\psi_1^*(s)}{\sqrt{1-s^2}} - M_{12}(x,t) \frac{\psi_2^*(s)}{\sqrt{1-s^2}} \right] dt = 0, \quad (27)$$

$$-\frac{H_{21}^\infty \psi_1^*(r)}{\sqrt{1-r^2}} - \frac{H_{22}^\infty}{\pi} \int_{-1}^1 \frac{\psi_2^*(s) ds}{(s-r)\sqrt{1-s^2}} + \frac{b}{\pi} \int_{-1}^1 \left[ M_{21}(x,t) \frac{\psi_1^*(s)}{\sqrt{1-s^2}} + M_{22}(x,t) \frac{\psi_2^*(s)}{\sqrt{1-s^2}} \right] dt = \frac{p_0}{2\mu_1}, \quad (28)$$

$$\int_{-1}^1 \frac{\psi_1^*(s)}{\sqrt{1-s^2}} dt = 0, \quad \int_{-1}^1 \frac{\psi_2^*(s)}{\sqrt{1-s^2}} dt = 0, \quad (29)$$

where  $\psi_1^*(s) = f_1^*(bs)$ ,  $\psi_2^*(s) = f_2^*(bs)$ .

Consider the equations (27), (28) at the nodes  $r_i = \cos\left(\frac{\pi i}{N}\right)$ ,  $i = 1, \dots, N-1$ , and apply the Gauss-Chebyshev quadrature formula for calculating the integrals:

$$\int_{-1}^1 \frac{\psi_m^*(s)}{\sqrt{1-s^2}} ds = \sum_{k=1}^N \frac{\pi}{N} \psi_m^*(s_k), \quad (30)$$

where  $s_k = \cos\left(\frac{2k-1}{2N} \pi\right)$ ,  $k = 1, \dots, N$ ,

we arrive at the system:

$$\begin{aligned}
 & -\frac{H_{11}^\infty}{N} \sum_{k=1}^N \frac{\psi_1^*(s_k)}{s_k - r_i} + H_{12}^\infty \frac{\psi_2^*(r_i)}{\sqrt{1-r_i^2}} - \frac{b}{N} \sum_{k=1}^N [M_{11}(x_i, t_k) \psi_1^*(s_k) - M_{12}(x_i, t_k) \psi_2^*(s_k)] = 0, \\
 & -H_{21}^\infty \frac{\psi_1^*(r_i)}{\sqrt{1-r_i^2}} - \frac{H_{22}^\infty}{N} \sum_{k=1}^N \frac{\psi_2^*(s_k)}{s_k - r_i} + \frac{b}{N} \sum_{k=1}^N [M_{21}(x_i, t_k) \psi_1^*(s_k) + M_{22}(x_i, t_k) \psi_2^*(s_k)] = \frac{p_0}{2\mu_1}, \quad (31)
 \end{aligned}$$

where  $x_i = br_i$ ,  $t_k = bs_k$ ,  $i = 1, \dots, N-1$ .

Since the nodes  $r_k$  are between the nodes  $s_k$  and  $s_{k+1}$ , we find  $\psi_m^*(r_k)$  through  $\psi_m^*(s_k)$  and  $\psi_m^*(s_{k+1})$  using linear interpolation:

$$\psi_m^*(r_k) = \frac{(r_k - s_{k+1})}{s_k - s_{k+1}} \psi_m^*(s_k) + \frac{(r_k - s_k)}{s_{k+1} - s_k} \psi_m^*(s_{k+1}), \quad m = 1, 2. \quad (32)$$

Substituting (32) into (31), we obtain:

$$\begin{aligned}
 & -\frac{H_{11}^\infty}{N} \sum_{k=1}^N \frac{\psi_1^*(s_k)}{s_k - r_i} + \sum_{k=1}^N \frac{H_{12}^\infty}{\sqrt{1-r_k^2}} \left[ \delta_{i,k} \frac{(r_k - s_{k+1})}{s_k - s_{k+1}} \psi_2^*(s_k) + \delta_{i,k+1} \frac{(r_k - s_k)}{s_{k+1} - s_k} \psi_2^*(s_{k+1}) \right] - \\
 & -\frac{b}{N} \sum_{k=1}^N [M_{11}(x_i, t_k) \psi_1^*(s_k) + M_{12}(x_i, t_k) \psi_2^*(s_k)] = 0. \quad (33)
 \end{aligned}$$

$$\begin{aligned}
 & -\sum_{k=1}^N \frac{H_{21}^\infty}{\sqrt{1-r_k^2}} \left[ \delta_{i,k} \frac{(r_k - s_{k+1})}{s_k - s_{k+1}} \psi_1^*(s_k) + \delta_{i,k+1} \frac{(r_k - s_k)}{s_{k+1} - s_k} \psi_1^*(s_{k+1}) \right] - \frac{H_{22}^\infty}{N} \sum_{k=1}^N \frac{\psi_2^*(s_k)}{s_k - r_i} + \\
 & + \frac{b}{N} \sum_{k=1}^N [M_{21}(x_i, t_k) \psi_1^*(s_k) + M_{22}(x_i, t_k) \psi_2^*(s_k)] = \frac{p_0}{2\mu_1}, \quad (34)
 \end{aligned}$$

where  $\delta_{i,k}$  are the Kronecker symbols,  $i = 1, \dots, N-1$ .

Applying the quadrature formula (30) to the equations (29), we obtain:

$$\sum_{k=1}^N \psi_1^*(s_k) = 0, \quad \sum_{k=1}^N \psi_2^*(s_k) = 0. \quad (35)$$

Equations (33)-(35) represent a system of  $2N$  linear algebraic equations with  $2N$  unknowns  $\psi_1^*(s_k)$  and  $\psi_2^*(s_k)$  ( $k = 1, 2, \dots, N$ ).

After solving the system, we obtain:

$$f_m(bs_k) = \frac{f_m^*(bs_k)}{b\sqrt{1-s_k^2}}, \quad m = 1, 2; \quad k = 1, \dots, N.$$



Then, based on (14), the derivatives of the displacement jumps  $f_1(x)$  and  $f_2(x)$  at the upper and lower crack faces, are found. Using further the formulas:

$$\langle u(x,0) \rangle = \int_{-b}^x f_1(x) dx, \quad \langle v(x,0) \rangle = \int_{-b}^x f_2(x) dx, \quad (36)$$

the displacement jumps:

$$\langle u(x,0) \rangle = u^{(1)}(x,0) - u^{(2)}(x,0) \quad \text{and} \quad \langle v(x,0) \rangle = v^{(1)}(x,0) - v^{(2)}(x,0)$$

are determined.

To find the stresses, we use the formulas (21) and (22). However, considering that  $f_1(x) = 0$  for  $x \notin (-b, b)$ , they take the following form:

$$\frac{\tau_{xy}^{(1)}(x,0)}{2\mu_1} = -\frac{H_{11}^\infty}{\pi} \int_{-b}^b \frac{f_1(t)}{t-x} dt - \frac{1}{\pi} \int_{-b}^b f_1(t) M_{11}(x,t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{12}(x,t) dt,$$

$$\frac{\sigma_{yy}^{(1)}(x,0)}{2\mu_1} = -\frac{H_{22}^\infty}{\pi} \int_{-b}^b \frac{f_2(t)}{t-x} dt + \frac{1}{\pi} \int_{-b}^b f_1(t) M_{21}(x,t) dt + \frac{1}{\pi} \int_{-b}^b f_2(t) M_{22}(x,t) dt, \quad x \notin (-b, b).$$

Performing an analysis similar to the outlined above, we arrive at the following formulas:

$$\frac{\tau_{xy}^{(1)}(x,0)}{2\mu_1} \approx -\frac{H_{11}^\infty}{N} \sum_{k=1}^N \frac{\psi_1^*(s_k)}{s_k - r} - \frac{b}{N} \sum_{k=1}^N [M_{11}(x, t_k) \psi_1^*(s_k) - M_{12}(x, t_k) \psi_2^*(s_k)], \quad (37)$$

$$\frac{\sigma_{yy}^{(1)}(x,0)}{2\mu_1} \approx -\frac{H_{22}^\infty}{N} \sum_{k=1}^N \frac{\psi_2^*(s_k)}{s_k - r} + \frac{b}{N} \sum_{k=1}^N [M_{21}(x, t_k) \psi_1^*(s_k) + M_{22}(x, t_k) \psi_2^*(s_k)], \quad (38)$$

where  $x \notin (-b, b)$ ,  $r = x/b$ .

According to [15], the energy release rate  $G$  during the crack propagation can be calculated by the formula:

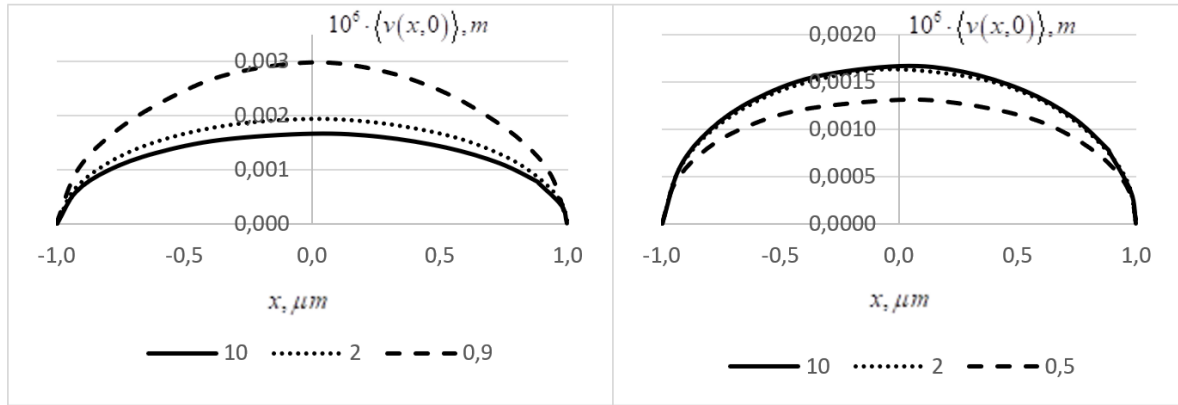
$$G = \frac{\pi b \mu_1}{\kappa_1 + 1} \hat{K}^2, \quad (39)$$

where  $\hat{K} = \sqrt{[f_1^*(b)]^2 + [f_2^*(b)]^2}$ .

### 3. RESULTS AND DISCUSSION

Numerical illustration of the obtained solution was carried out for a microcrack with a length of  $2 \mu m$  and different thicknesses of two infinite layers in the range from  $0,5 \mu m$  to

10  $\mu\text{m}$  (Fig. 2, 3). Additionally, it was assumed that  $\nu_1 = \nu_2 = 0,3$ , the Young's modulus for each layer varies within the range from  $2,2 \cdot 10^{-2} \text{ N}/\mu\text{m}^2$  to  $26 \cdot 10^{-2} \text{ N}/\mu\text{m}^2$  and internal pressure  $p_0 = 10^{-5} \text{ N}/\mu\text{m}^2$ .

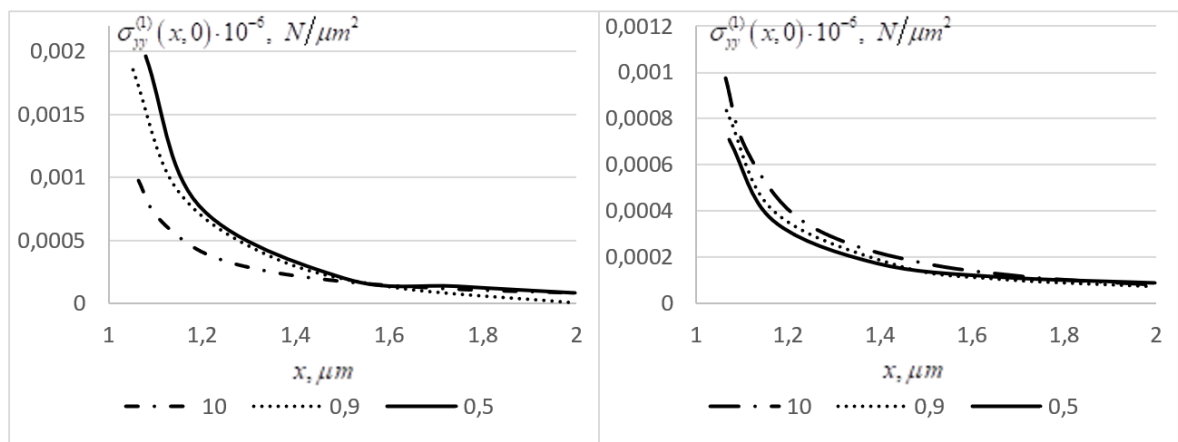


a)

b)

**Figure 2.** Crack opening at:

- a)  $h_1 = 0,9\text{--}10 \mu\text{m}$ ,  $h_2 = 10 \mu\text{m}$  ( $E_1 = 0,026 \text{ N}/\mu\text{m}^2$ ,  $E_2 = 0,022 \text{ N}/\mu\text{m}^2$ )
- b)  $h_1 = 10 \mu\text{m}$ ,  $h_2 = 0,5\text{--}10 \mu\text{m}$  ( $E_1 = 0,026 \text{ N}/\mu\text{m}^2$ ,  $E_2 = 0,022 \text{ N}/\mu\text{m}^2$ )



a)

b)

**Figure 3.** The stress at the extension of the crack at:

- a)  $h_1 = 0,5\text{--}10 \mu\text{m}$ ,  $h_2 = 10 \mu\text{m}$  ( $E_1 = 0,026 \text{ N}/\mu\text{m}^2$ ,  $E_2 = 0,022 \text{ N}/\mu\text{m}^2$ )
- b)  $h_1 = 10 \mu\text{m}$ ,  $h_2 = 0,5\text{--}10 \mu\text{m}$  ( $E_1 = 0,026 \text{ N}/\mu\text{m}^2$ ,  $E_2 = 0,022 \text{ N}/\mu\text{m}^2$ )

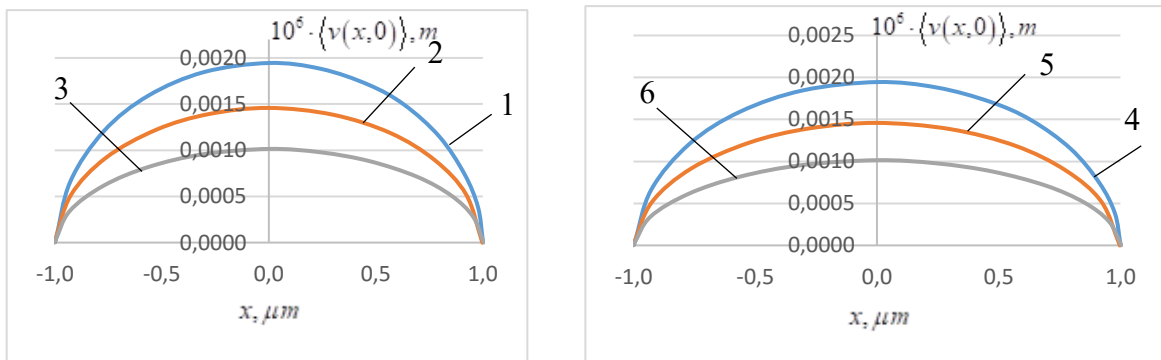
It should be noted that as the thickness of the upper strip decreases, a significant increase in the crack opening and the energy release rate is observed (Table 1). On the other hand, when the thickness of the lower strip decreases, a significant change is observed only for thicknesses smaller than  $0.5 \mu\text{m}$ , which may indicate that the crack opening values are approaching the possible limit for the applicability of linear elasticity theory.

**Table 1**

The change in the energy release rate

The thickness of the upper strip $h_1, \mu m$	The thickness of the lower strip $h_2, \mu m$	ERR·10 <sup>-8</sup> N·m, $E_1 = 0,026 N/\mu m^2$ , $E_2 = 0,022 N/\mu m^2$	$E_1$ , $N/\mu m^2$	$E_2$ , $N/\mu m^2$	ERR·10 <sup>-8</sup> N·m, $h_1 = 2 \mu m$ , $h_2 = 10 \mu m$
10	10	2,77	0,026	0,022	3,68
5		2,89	0,052		4,13
2		3,68	0,13		6,27
0,9		6,94	0,26		9,88
0,5		15,1			
10	10	2,77	0,026	0,022	3,68
	5	2,76		0,044	1,98
	2	2,66		0,11	1,16
	0,9	2,32		0,22	0,93
	0,5	1,92			

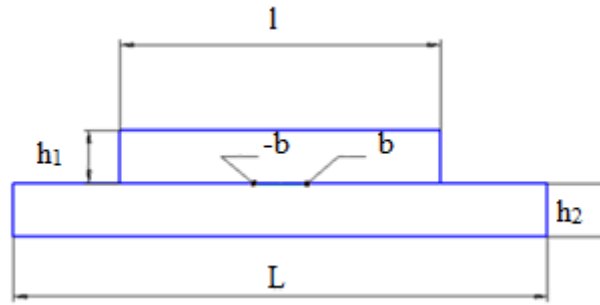
Figure 4 presents graphs of crack opening with variations in Young's modulus for the upper and lower thin layers. An increase in Young's modulus values results in a decrease in crack opening. However, the energy release rate at the crack edge for the upper layer significantly increases in this case, whereas, with an increase in Young's modulus for the lower layer, there is a marked decrease in the energy release rate for the coating (Table 1).



- a)  $h_1 = 2 \mu m, h_2 = 10 \mu m$  (1 –  $E_1 = 0,026 N/\mu m^2, E_2 = 0,022 N/\mu m^2$ ; 2 –  $E_1 = 0,052 N/\mu m^2, E_2 = 0,022 N/\mu m^2$ ; 3 –  $E_1 = 0,26 N/\mu m^2, E_2 = 0,022 N/\mu m^2$ )
- b)  $h_1 = 2 \mu m, h_2 = 10 \mu m$  (4 –  $E_1 = 0,026 N/\mu m^2, E_2 = 0,022 N/\mu m^2$ ; 5 –  $E_1 = 0,026 N/\mu m^2, E_2 = 0,044 N/\mu m^2$ ; 6 –  $E_1 = 0,026 N/\mu m^2, E_2 = 0,22 N/\mu m^2$ )

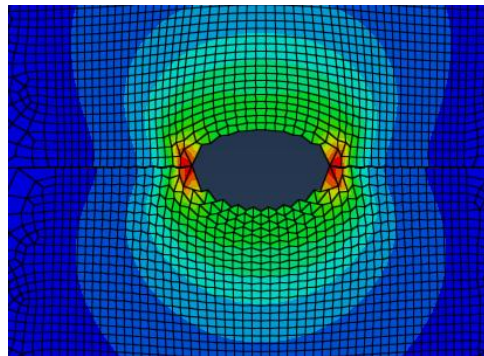
**Figure 4.** Crack opening

For the case of a thin overlay of finite length, which is in contact with a thin strip of finite dimensions (Fig. 5), the analysis was conducted using the finite element method (FEM). A microcrack with a length of  $2 \mu m$  was considered, with overlay and strip thicknesses in the range of  $0,5-10 \mu m$ . Additionally, the parameters  $L = 50 \mu m, l = 50 \mu m$ . Other relevant values were chosen  $\nu = 0,3, E_1 = 0,026-0,26 N/\mu m^2, E_2 = 0,022-0,22 N/\mu m^2, p_0 = 10 \cdot 10^{-6} N/\mu m^2$ .



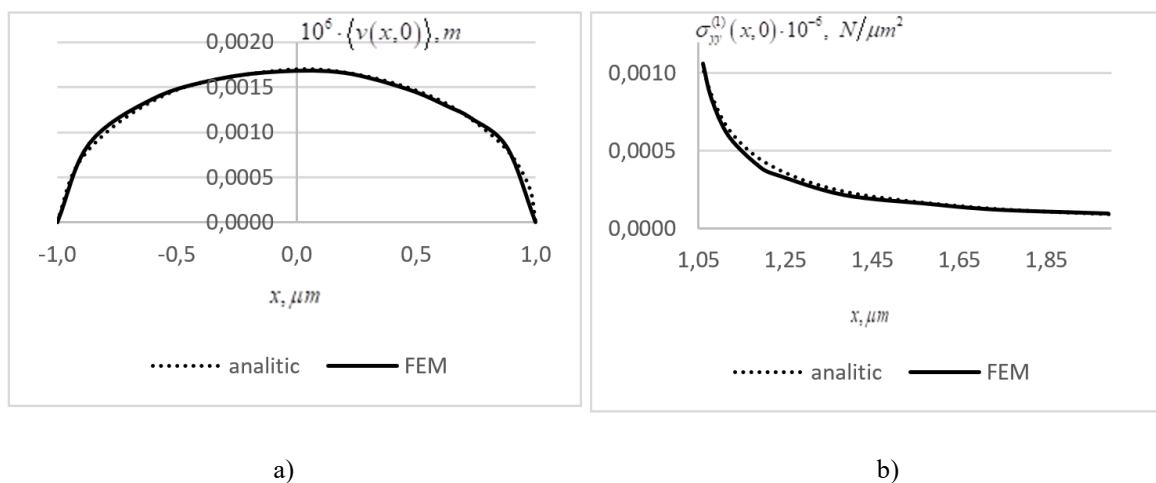
**Figure 5.** Thin overlay for FEM analysis

In the FEM modeling, the mesh refinement was performed in the vicinity of the crack (Fig. 6). The degree of refinement, as well as the element size, was varied depending on the overlay thickness.



**Figure 6.** An example of a mesh with the distribution of von Mises stresses at  $h_1 = 5 \mu m$ ,  $h_2 = 10 \mu m$  ( $E_1 = 0,026 N/\mu m^2$ ,  $E_2 = 0,022 N/\mu m^2$ )

The obtained distributions of stresses, crack opening, and energy release rate for different values of the characteristics of the thin overlay and strip are presented. For the case where the thickness of the overlay is half that of the strip, and the stiffnesses are approximately equal, a comparison between the analytical and numerical results was conducted (Fig. 7).



**Figure 7.** A comparative analysis of the crack opening (a) and the stress at the extension of the crack (b) at:  $h_1 = 5 \mu m$ ,  $h_2 = 10 \mu m$  ( $E_1 = 0,026 N/\mu m^2$ ,  $E_2 = 0,022 N/\mu m^2$ )

The presented graphs demonstrate good agreement between the results obtained using the analytical method and FEM. Both analytical and numerical methods were used to analyze the change in the crack opening shape with varying overlay and strip thicknesses, or changes in material stiffness, as well as the variations in the energy release rate depending on the changes in the thicknesses of the overlay and strip.

#### 4. CONCLUSIONS

This work investigated the plane deformation of a crack located between two isotropic, linearly elastic, infinite layers, with the lower layer fixed rigidly. The crack is subjected to uniform internal pressure, and the crack opening and stress state were determined by solving the corresponding boundary value problem. Using Fourier integral transforms, a system of differential equations was constructed, from which analytical expressions were derived for the stresses and displacements in the layers.

Additionally, a numerical analysis was conducted using the finite element method (FEM) to verify the analytical results. Excellent agreement was found between the analytical and FEM results. Numerical calculations showed a significant influence of the upper layer's thickness on the crack opening and energy release rate; these parameters increase with decreasing upper layer thickness. It is therefore important to account for this effect in practical problems involving crack formation in multilayer materials.

These detailed results will contribute to the development of more fracture-resistant composites, especially in microelectronics applications, where microcracks can compromise device reliability.

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## Appendix

Expressions for the functions  $H_{ij}(\alpha)$ :

$$\begin{aligned}
 H_{11}[\alpha] &= \frac{1}{Zn[\alpha]} \left( -4e^{-2\alpha h_2} \alpha (1 + \kappa_1) (1 + e^{2\alpha h_2} \kappa_2) h_1 (e^{2\alpha h_2} + \kappa_2 - 2\alpha h_2) + \right. \\
 &\quad \left. + 4e^{-2\alpha h_2} (-1 + e^{2\alpha h_2}) K \alpha^2 (1 + \kappa_2) h_1^2 (\kappa_2 + e^{2\alpha h_2} \kappa_2 - 2\alpha h_2) + \right. \\
 &\quad \left. + 4 \sinh[\alpha h_1] \left( -((1 + \kappa_1) \cosh[\alpha h_1] (1 + \kappa_2^2 + 2\kappa_2 \cosh[2\alpha h_2])) - 2K \kappa_2 (1 + \kappa_2) \sinh[\alpha h_1] \sinh[2\alpha h_2] + \right. \right. \\
 &\quad \left. \left. + 2\alpha ((1 + \kappa_1) (e^{-2\alpha h_2} + \kappa_2) \cosh[\alpha h_1] + (1 - e^{-2\alpha h_2}) K (1 + \kappa_2) \sinh[\alpha h_1]) h_2 \right) \right); \\
 H_{12}[\alpha] &= \frac{1}{Zn[\alpha]} \left( 2(-1 + \kappa_1 - 2K \kappa_2 + (-1 + 2K + \kappa_1) \kappa_2^2) - 2(-1 + \kappa_1 - 2K \kappa_2 + (-1 + 2K + \kappa_1) \kappa_2^2) \cosh[2\alpha h_1] - \right. \\
 &\quad \left. - 2\kappa_2 (-1 + K + \kappa_1 - K \kappa_2) \cosh[2\alpha (h_1 - h_2)] + \kappa_2 (4(-1 + K + \kappa_1 - K \kappa_2) \cosh[2\alpha h_2] + \right. \\
 &\quad \left. + (-2(-1 + K + \kappa_1) + K \kappa_2) \cosh[2\alpha (h_1 + h_2)] + K \kappa_2 (\cosh[\alpha (2h_1 + h_2)] + \sinh[2\alpha (h_1 + h_2)] - \sinh[\alpha (2h_1 + h_2)]) \right) + \\
 &\quad \left. + 2\alpha \left( (2K + e^{-2\alpha(h_1+h_2)} (-1 + K + \kappa_1) - e^{-\alpha(2h_1+h_2)} K \kappa_2 - 2(-1 + K + \kappa_1) \kappa_2 + e^{2\alpha(h_1-h_2)} (-1 + K + \kappa_1 - K \kappa_2) - \right. \right. \\
 &\quad \left. \left. - 2e^{-2\alpha h_2} (-1 + K + \kappa_1 - K \kappa_2) + e^{-2\alpha h_1} (-K + (-1 + K + \kappa_1) \kappa_2) + e^{2\alpha h_1} (-K + (-1 + K + \kappa_1) \kappa_2) \right) h_2 + \right. \\
 &\quad \left. + 2e^{-2\alpha h_2} \alpha h_1^2 \left( -e^{4\alpha h_2} (2 + K(-1 + \kappa_2)) \kappa_2 - (2 + K(-1 + \kappa_2)) (\kappa_2 - 2\alpha h_2) - \right. \right. \\
 &\quad \left. \left. - 2e^{2\alpha h_2} (1 + \kappa_2 (K + \kappa_2 - K \kappa_2) + \alpha (-K + (-2 + K) \kappa_2) h_2) \right) \right); \\
 H_{21}(\alpha) &= \frac{1}{Zn[\alpha]} \left( -4(-1 + \kappa_1 - 2K \kappa_2 + (-1 + 2K + \kappa_1) \kappa_2^2 + 2\kappa_2 (-1 + K + \kappa_1 - K \kappa_2) \cosh[2\alpha h_2]) \sinh[\alpha h_1]^2 + \right. \\
 &\quad \left. + 4e^{-2\alpha h_2} \alpha \left( 2(-1 + K + \kappa_1 - K \kappa_2 + e^{2\alpha h_2} (K + (-1 + 3K + \kappa_1) \kappa_2)) \sinh[\alpha h_1]^2 h_2 + \right. \right. \\
 &\quad \left. \left. + \alpha h_1^2 \left( -e^{4\alpha h_2} (2 + K(-1 + \kappa_2)) \kappa_2 - (2 + K(-1 + \kappa_2)) (\kappa_2 - 2\alpha h_2) - \right. \right. \right. \\
 &\quad \left. \left. \left. - 2e^{2\alpha h_2} (1 + \kappa_2 (K + \kappa_2 - K \kappa_2) + \alpha (K - 2\kappa_2 + 3K \kappa_2) h_2) \right) \right) \right); \\
 H_{22}(\alpha) &= \frac{1}{Zn[\alpha]} \left( 4 \left( e^{-2\alpha h_2} \alpha (1 + \kappa_1) (1 + e^{2\alpha h_2} \kappa_2) h_1 (e^{2\alpha h_2} + \kappa_2 - 2\alpha h_2) + \right. \right. \\
 &\quad \left. \left. + e^{-2\alpha h_2} (1 + e^{2\alpha h_2}) K \alpha^2 (1 + \kappa_2) h_1^2 \left( (-1 + e^{2\alpha h_2}) \kappa_2 + 2\alpha h_2 \right) + \right. \right. \\
 &\quad \left. \left. + \sinh[\alpha h_1] \left( -((1 + \kappa_1) \cosh[\alpha h_1] (1 + \kappa_2^2 + 2\kappa_2 \cosh[2\alpha h_2])) - 2K \kappa_2 (1 + \kappa_2) \sinh[\alpha h_1] \sinh[2\alpha h_2] + \right. \right. \right. \\
 &\quad \left. \left. \left. + 2\alpha ((1 + \kappa_1) (e^{-2\alpha h_2} + \kappa_2) \cosh[\alpha h_1] + (-1 - e^{-2\alpha h_2}) K (1 + \kappa_2) \sinh[\alpha h_1]) h_2 \right) \right) \right);
 \end{aligned}$$

where

$$\begin{aligned} Zn[\alpha] = & 8K\alpha^2(1+\kappa_1)(1+\kappa_2)h_1h_2 - \\ & -8e^{-2\alpha h_2}\alpha^2(-1+e^{2\alpha h_2}(-1+K)\kappa_2-K\kappa_2)h_1^2(\kappa_2-K\kappa_2+e^{2\alpha h_2}(1+K\kappa_2)+2(-1+K)\alpha h_2)+ \\ & +2e^{-2\alpha(h_1+h_2)}(1-e^{2\alpha h_2}(-1+K)\kappa_2+K\kappa_2+e^{2\alpha(h_1+h_2)}(K+\kappa_1)\kappa_2+e^{2\alpha h_1}(\kappa_1-K\kappa_2))\times \\ & \times(-e^{2\alpha h_1}(-1+K)\kappa_2+(K+\kappa_1)\kappa_2+e^{2\alpha h_2}(\kappa_1-K\kappa_2)+e^{2\alpha(h_1+h_2)}(1+K\kappa_2)+2\alpha(e^{2\alpha h_1}(-1+K)-K-\kappa_1)h_2). \end{aligned}$$

УДК 539.3

## ОСОБЛИВОСТІ ДЕФОРМУВАННЯ ДВОХ ТОНКИХ ПОЛОС З МІКРОТРИЩИННОЮ НА МЕЖІ ЇХ З'ЄДНАННЯ

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**Резюме.** Детально розглянуто задачу про плоску деформацію тріщини, що знаходиться між двома ізотропними, лінійно пружними шарами, один з яких жорстко закріплений. Для розв'язання цієї задачі було використано метод інтегральних перетворень Фур'є, який дозволив звести початкову систему диференціальних рівнянь у частинних похідних до системи звичайних диференціальних рівнянь. На її основі побудовано систему сингулярних інтегральних рівнянь (СІР), яка задовольняє крайові умови задачі. Ця система описує напружено-деформований стан біматеріальної полоси з тріщиною. Для розв'язання системи сингулярних інтегральних рівнянь застосовано метод дискретизації. Суть методу полягає в тому, що неперервна система рівнянь замінюється на дискретну, що дозволяє отримати наближений розв'язок. У даному випадку дискретизація призвела до системи лінійних алгебраїчних рівнянь (СЛАР).

Розв'язавши систему лінійних алгебраїчних рівнянь, отримано вирази для розкриття тріщини та розподілу напружень на межі поділу матеріалів. Ці результати є ключовими для аналізу механічної поведінки тріщини та оцінювання її впливу на конструкцію.

На основі отриманих даних про розкриття тріщини та розподіл напружень було обчислено швидкість звільнення енергії (ШЗЕ) у вершинах тріщини. ШЗЕ є важливим параметром, який характеризує енергетичний стан тріщини та її схильність до росту. Для ілюстрації отриманих результатів проведено чисельне моделювання. Зокрема, побудовано графіки розкриття тріщини та залежності напружень для різних товщин шарів і модулів Юнга. Ці графіки демонструють вплив геометричних та матеріальних параметрів на поведінку тріщини.

Отримані аналітичні розв'язки порівняно з чисельними розв'язками, отриманими методом скінченних елементів (МСЕ). Порівняння показало гарне узгодження результатів для випадку мікротріщини при змінних значеннях характеристик тонкої накладки та нижнього шару.

Особливу увагу приділено дослідженню впливу товщини накладки на швидкість звільнення енергії. Виявлено значний вплив цього параметра на ШЗЕ, що підкреслює важливість його врахування при проектуванні багатошарових конструкцій.

Проведене дослідження дозволяє отримати детальну інформацію про механічну поведінку тріщини, розташованої між двома ізотропними шарами. Отримані результати можна використати для прогнозування розвитку тріщин та оцінювання міцності конструкцій.

**Ключові слова:** мікротріщина, напружено-деформований стан, сингулярні інтегральні рівняння, швидкість звільнення енергії, розкриття тріщини.

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